



**Quantitative Monitoring of the Underwater
Environment: Results of the International Marine
Science and Technology Event MOQESM'14 in
Brest, France (Ocean Engineering &
Oceanography)**

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Quantitative Monitoring of the Underwater Environment: Results of the International Marine Science and Technology Event MOQESM'14 in Brest, France (Ocean Engineering & Oceanography)

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This volume constitutes the results of the International Conference on Underwater Environment, MOQESM'14, held at “Le Quartz” Conference Center in Brest, France, on October 14-15, 2014, within the framework of the 9th Sea Tech Week, International Marine Science and Technology Event. The objective of MOQESM'14 was to bring together researchers from both academia and industry, interested in marine robotics and hydrography with application to the coastal environment mapping and underwater infrastructures surveys.

The common thread of the conference is the combination of technical control, perception, and localization, typically used in robotics, with the methods of mapping and bathymetry.

The papers presented in this book focus on two main topics.

Firstly, coastal and infrastructure mapping is addressed, focusing not only on hydrographic systems, but also on positioning systems, bathymetry, and remote sensing. The proposed methods rely on acoustic sensors such as side scan sonars, multibeam echo sounders, phase-measuring bathymetric sonars, as well as optical systems such as underwater laser scanners. Accurate underwater positioning is also addressed in the case of the use of a single acoustic beacon, and the latest advances in increasing the vertical precision of Global Navigation Satellite System (GNSS) are also presented.

Most of the above mentioned works are closely related to autonomous marine vehicles. Consequently, the second part of the book describes some works concerning the methods associated with such type of vehicles. The selected papers focus on autonomous surface or underwater vehicles, detailing new approaches for localization, modeling, control, mapping, obstacle detection and avoidance, surfacing, and software development. Some of these works imply acoustics sensing as well as image processing. Set membership methods are also used in some papers.

The applications of the work presented in this book concern in particular oceanography, monitoring of oil and gas infrastructures, and military field.

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